

## PROCESS FOR ENHANCING THE EXISTING AMBIENCE, IMAGING, DEPTH, CLARITY AND SPACIOUSNESS OF SOUND RECORDINGS

**Abstract:** Taking maximum advantage of the Madsen effect and means of extending the fusion zone; incoming mono or stereo audio is processed by the following equations, where the delay for any repetition is within the fusion zone for attenuations K.

Stereo result (1, 2):

1) Ch. A = source ch. A, add (ch. B source delayed by Haas delay  $D_1$ , attenuated by attn.  $K_1$ ), subtract (ch. A source delayed by  $D_2$ , attn. by  $K_2$ ), subtract (ch. B source delayed by  $D_3$ , attn. by  $K_3$ ), add (ch. A source delayed by  $D_4$ , attn. by  $K_4$ )....

2) Ch. B = source channel B, subtract (ch. A source delayed by Haas delay  $D_5$ , attn. by  $K_5$ ), subtract (ch. B source delayed by  $D_6$ , attn. by  $K_6$ ), add (ch. A source delayed by  $D_7$ , attn. by  $K_7$ ), add (ch. B source delayed by  $D_8$ , attn. by  $K_8$ )....

Extracting front channel ambience to the surrounds (3, 4):

3) Surround Ch. A = invert (ch. B source delayed by Haas delay  $D_9$ , attn. by  $K_9$ ), add (ch. A source delayed by  $D_{10}$ , attn. by  $K_{10}$ ), add (ch. B source delayed by  $D_{11}$ , attn. by  $K_{11}$ )....

4) Surround Ch. B = (ch. A source delayed by Haas delay  $D_{12}$ , attn. by  $K_{12}$ ), add (ch. B source delayed by  $D_{13}$ , attn. by  $K_{13}$ ), subtract (ch. A source delayed by  $D_{14}$ , attn. by  $K_{14}$ )....

Alternatively: Some or all of the subtracted (inverted) terms may be added. Some terms after the first summation may be eliminated. For equations 3, 4, an A minus B matrix may be used instead of the direct channel sources.